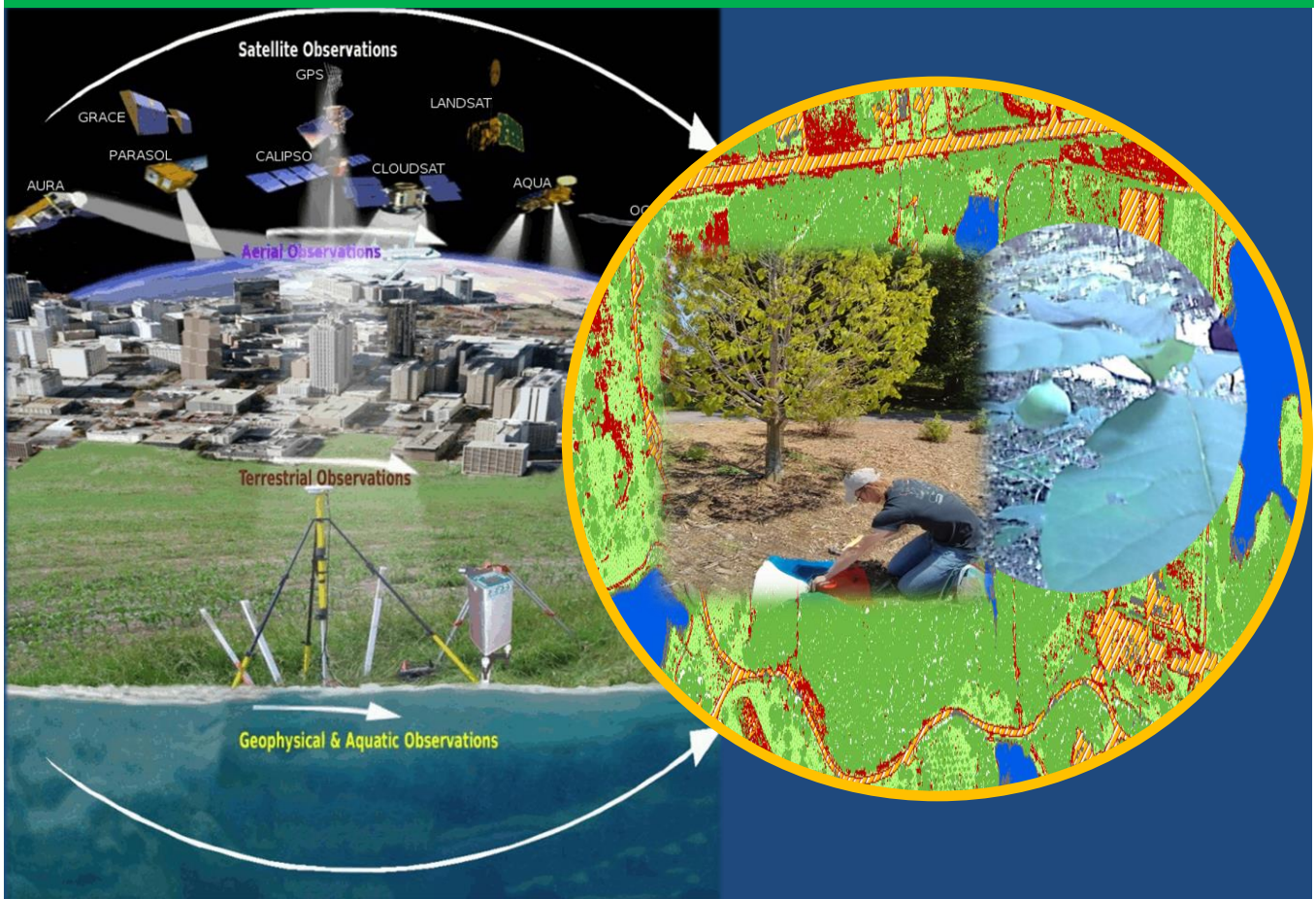


# MAPPING THE SPATIAL DISTRIBUTION OF PAWPAW IN KENTUCKY – PILOT SITE GUERRILLA CREEK



Authors: B. Acharya, K. Pomper, B. Gyawali, K. Bhattarai,  
A. Berry, T. Tsegaye



## ABSTRACT

Native pawpaw patches serve an important role in forest ecosystems around streams and rivers in terms of fruit production, soil erosion control, enhancing insect biodiversity, and possibly resisting establishment of invasive plant species. Field observations at several locations in Kentucky suggest that areas where pawpaws are well established tend to have a presence of fewer invasive plant species. How pawpaw patches have spread throughout the southeastern United States is not well understood. The objective of this study is to find a suitable model(s) to map spatial concentration of pawpaw patches and invasive species in central Kentucky utilizing multitemporal imageries captured from airborne and satellite platforms. Upscaling and down scaling of multi-temporal-spectral-spatial existing imageries are used to develop the model(s). Multispatial resolutions airborne imageries from 5-cm to 100-cm, and satellite imageries of 15-meter are tested. Multispectral: panchromatic, color-color infrared, near infrared imageries collected during different time covering the Guerilla Creek watershed at Bernheim Arboretum and Research Forest as a pilot site are used. A priori spectral signatures of pawpaw, spicebush, and other plants will be used during the model development for creating vegetation indices, measure density, slope, aspects, crown diameter, and height. The model developed at this pilot site will be expanded to cover other areas such as the central Kentucky region.

- MULTI-TEMPORAL-SPECTRAL-SPATIAL
- GUERILLA CREEK AT BERNHEIM ARBORETUM
- IMAGE CLASSIFICATIONS
- SPATIAL DISTRIBUTION OF PAWPAW
- RESULTS
- ACCURACY STANDARDS



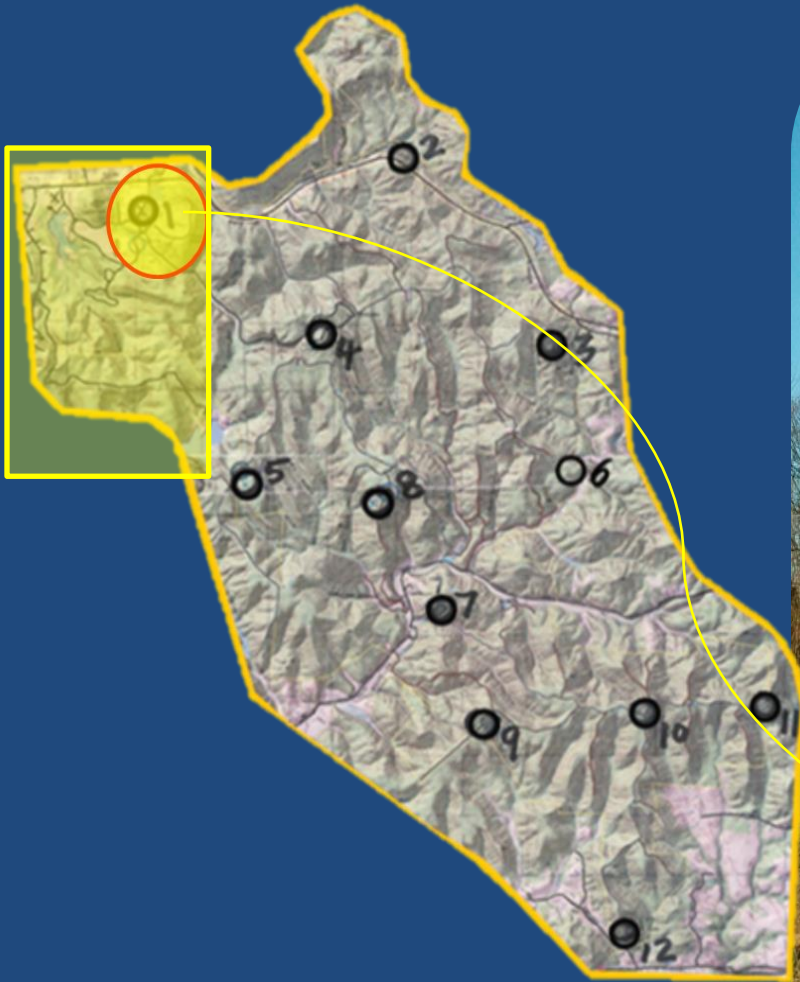
# RESEARCH LOCATION



Source: Google + Bernheim+ US Census + EMI



# GNSS GEODETIC NETWORK – OPUS STATIC

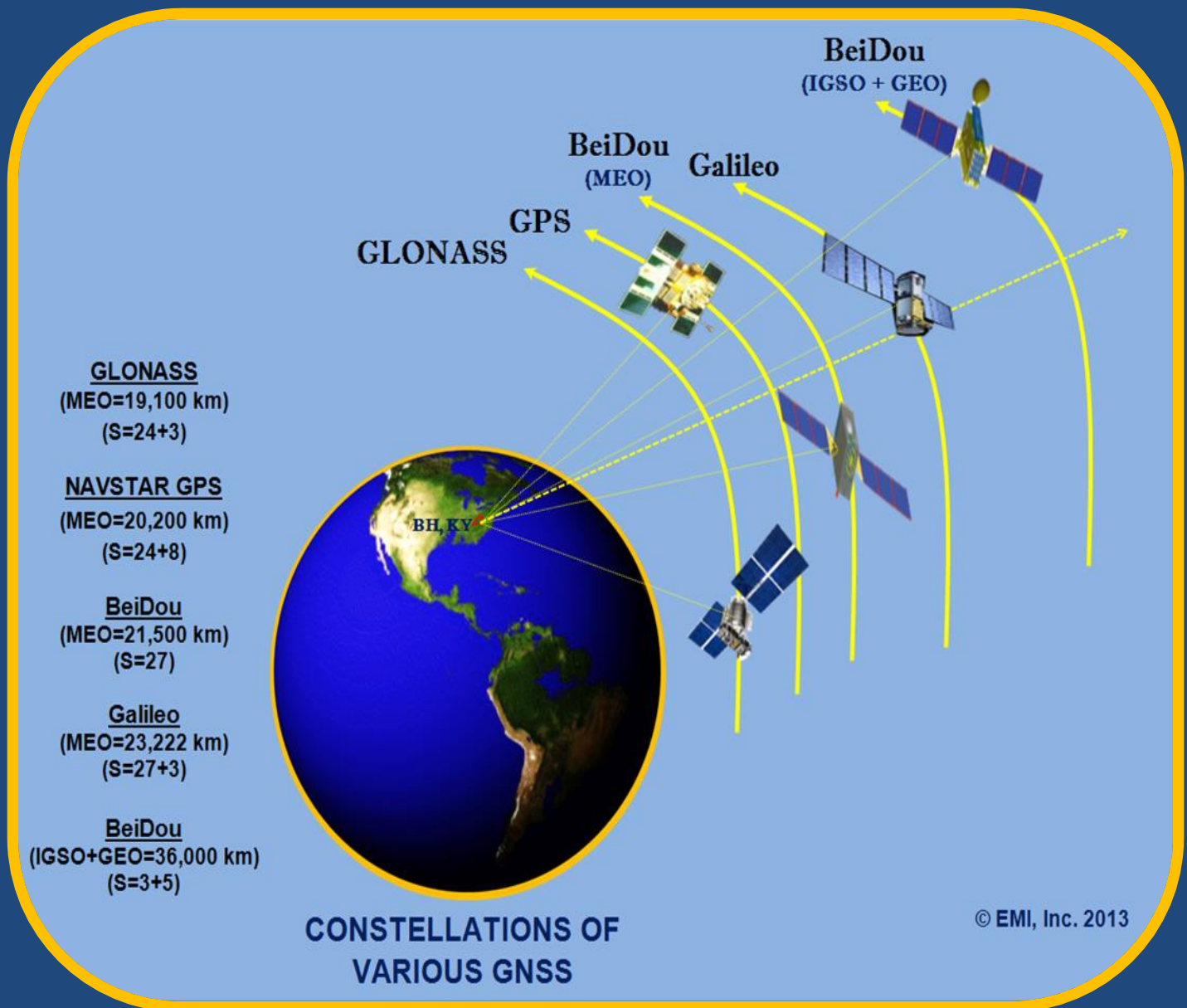


BERNHEIM ARBORETUM  
&  
RESEARCH FOREST



**GLOBAL NAVIGATION SATELLITE SYSTEM (GNSS)  
ONLINE POSITIONING USER SERVICE (OPUS)**

# VARIOUS GNSS



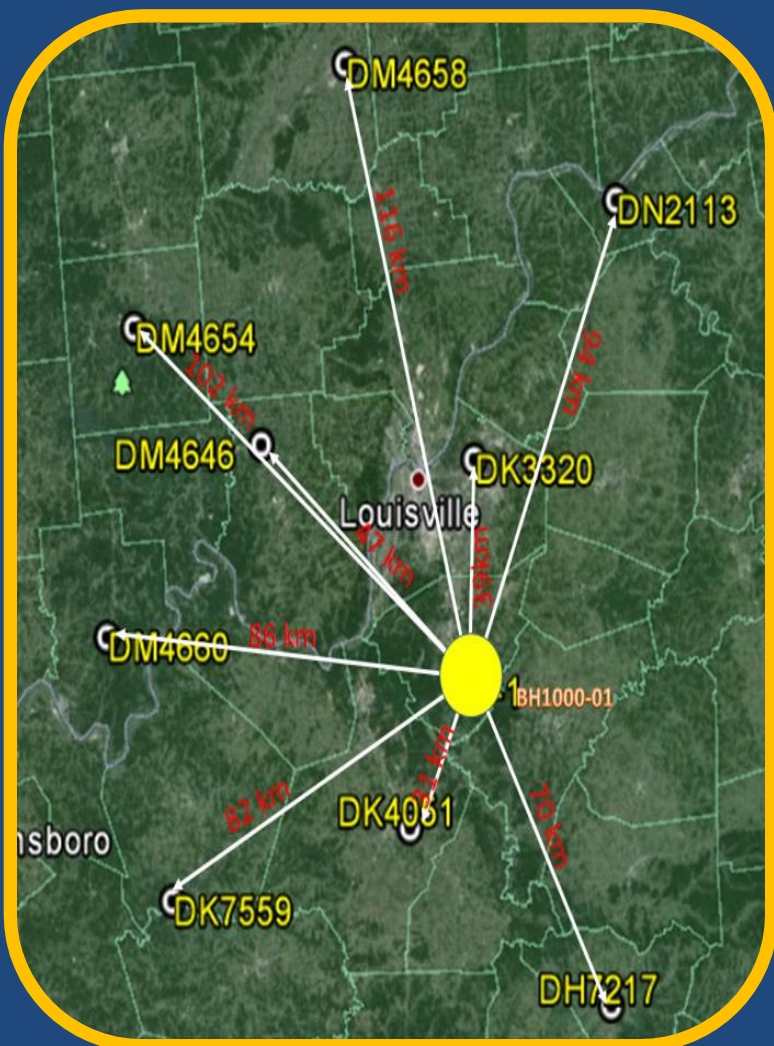
ALL NAVIGATION SATELLITES HAVE MEDIUM EARTH ORBITING (MEO) CONFIGURATIONS EXCEPT BEIDOU SYSTEM

BEIDOU NAVIGATION SATELLITE SYSTEM HAS THREE DIFFERENT ORBITS:

MEO,  
INCLINED GEOSYNCHRONOUS SATELLITE ORBIT (IGSO), &  
GEOSTATIONARY EARTH ORBIT (GEO)



# OPUS RAPID STATIC NETWORK COMPUTATION



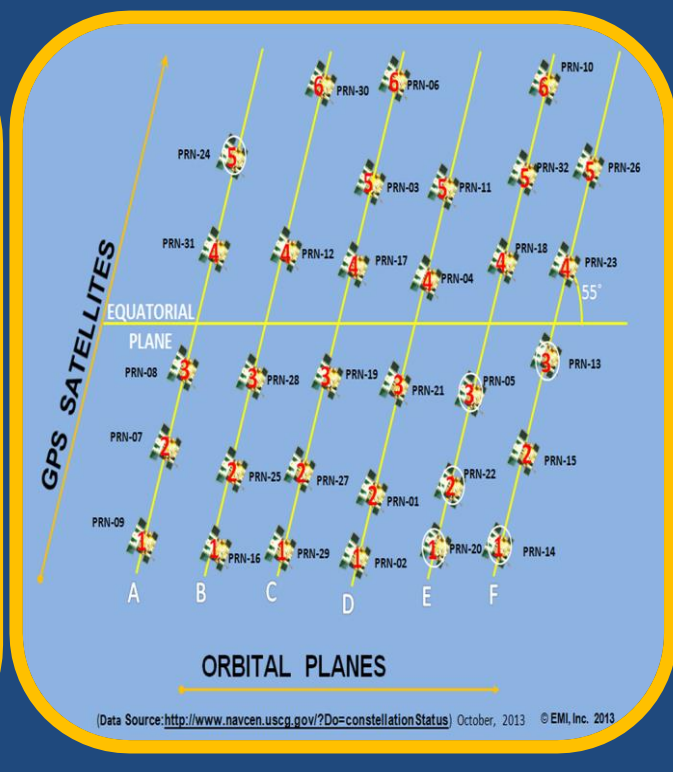
## NGS OPUS-RS SOLUTION REPORT

=====

All computed coordinate accuracies are listed as 1-sigma RMS values.  
 For additional information: <http://www.ngs.noaa.gov/OPUS/about.jsp#accuracy>  
 USER: bishwa@earthmapping.com DATE: March 30, 2013  
 RINEX FILE: 1776072u.13o TIME: 01:30:27 UTC  
 SOFTWARE: rsgps 1.37 RS94.prl 1.87 START: 2013/03/13 20:41:00  
 EPHEMERIS: igs17313.eph [precise] STOP: 2013/03/13 21:01:30  
 NAV FILE: brdc0720.13n OBS USED: 1278 / 1494 : 86%  
 ANT NAME: TRMR8\_GNSS3 NONE QUALITY IND. 25.64/ 6.65  
 ARP HEIGHT: 2.00 NORMALIZED RMS: 0.304  
 REF FRAME: NAD\_83(2011)(EPOCH:2010.0000) IGS08 (EPOCH:2013.19690)  
 X: 381579.972(m) 0.004(m) 381579.181(m) 0.004(m)  
 Y: -5023243.164(m) 0.029(m) -5023241.739(m) 0.029(m)  
 Z: 3898876.369(m) 0.024(m) 3898876.262(m) 0.024(m)  
 LAT: 37 55 26.59945 0.007(m) 37 55 26.62623 0.007(m)  
 E LON: 274 20 38.43321 0.003(m) 274 20 38.40534 0.003(m)  
 W LON: 85 39 21.56679 0.003(m) 85 39 21.59466 0.003(m)  
 EL HGT: 127.554(m) 0.037(m) 126.321(m) 0.037(m)  
 ORTHO HGT: 160.895(m) 0.039(m) [NAVD88 (Computed using GEOID12A)]  
 UTM COORDINATES STATE PLANE COORDINATES  
 UTM (Zone 16) SPC (1600 KY1Z)  
 Northing (Y) [meters] 4198240.471 1176546.346  
 Easting (X) [meters] 618124.681 1508264.785  
 Convergence [degrees] 0.82614564 0.05771797  
 Point Scale 0.99977186 0.99990529  
 Combined Factor 0.99975185 0.99988528  
 US NATIONAL GRID DESIGNATOR: 16SFG1812498240(NAD 83)

## BASE STATIONS USED

DK4051 KYTD KY HWY DIST 4 CORS ARP N374054.459 W0855102.411 31890.9  
 DK3320 KYTE KY HWY DIST 5 CORS ARP N381635.939 W0853554.200 39463.0  
 DM4646 INFC FALLS CITY CORS ARP N382048.315 W0854458.830 47633.4  
 DH7217 KYCP CAMPBELLSVILLE U CORS ARP N372032.022 W0852100.223 69996.9  
 DK7559 KYRR ROUGH RIVER SRP CORS ARP N373635.880 W0863008.698 82324.7  
 DM4660 INTC TELL CITY CORS ARP N380336.152 W0863732.842 86517.1  
 DN2113 KYBU GEN BUTLER SRP CORS ARP N384025.770 W0850917.721 94063.4  
 DM4654 INPA PAOLI CORS ARP N383357.706 W0862930.634 102136.9  
 DM4658 INSY SEYMOUR CORS ARP N385736.280 W0855142.432 116399.4



# AERIAL MISSION PLANNING

## Digital Metric Mapping Camera

# Final Resolution

5-cm

# Flying Height

2700' AGL

# Aerial Targets

22" x 22"

## Ground Control Points

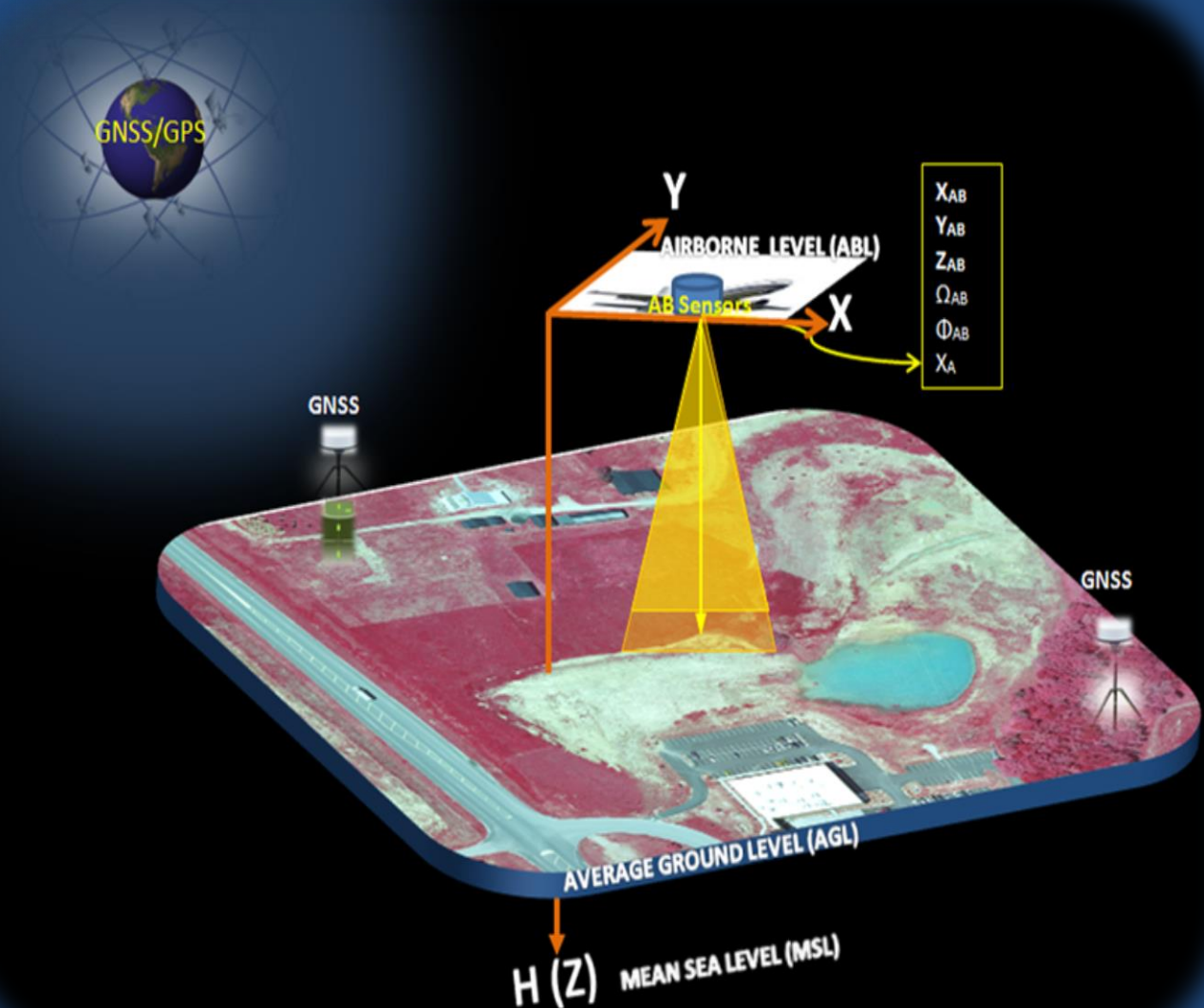
9

## Ground Sampling Distance (GSD)

1.97"

# LiDAR Data GSD

1-meter





# PHOTO CONTROL POINTS FOR BERNHEIM RESEARCH (GUERILLA CREEK) SITE

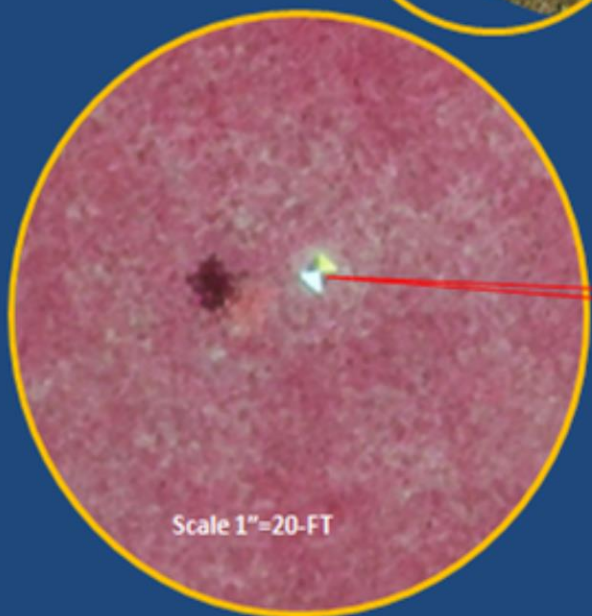
E43-N61	E44-N61	E45-N61	E46-N61	E47-N61	E48-N61
E43-N60	E44-N60	E45-N60	E46-N60	E47-N60	E48-N60
E43-N59	E44-N59	E45-N59	E46-N59	E47-N59	E48-N59
E43-N58	E44-N58	E45-N58	E46-N58	E47-N58	E48-N58
E43-N57	E44-N57	E45-N57	E46-N57	E47-N57	E48-N57
E43-N56	E44-N56	E45-N56	E46-N56	E47-N56	E48-N56
E43-N55	E44-N55	E45-N55	E46-N55	E47-N55	E48-N55
E43-N54	E44-N54	E45-N54	E46-N54	E47-N54	E48-N54
E43-N53	E44-N53	E45-N53	E46-N53	E47-N53	E48-N53
E43-N52	E44-N52	E45-N52	E46-N52	E47-N52	E48-N52
E43-N51	E44-N51	E45-N51	E46-N51	E47-N51	E48-N51
E43-N50	E44-N50	E45-N50	E46-N50	E47-N50	E48-N50



NEW AERIAL TARGETS DESIGNED AND USED FOR COLOR AND CIR MULTISPECTRAL MAPPING



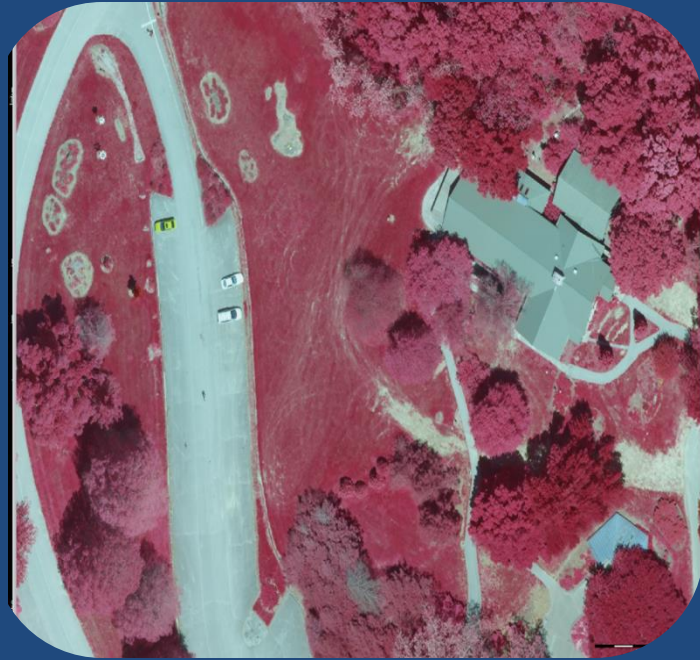
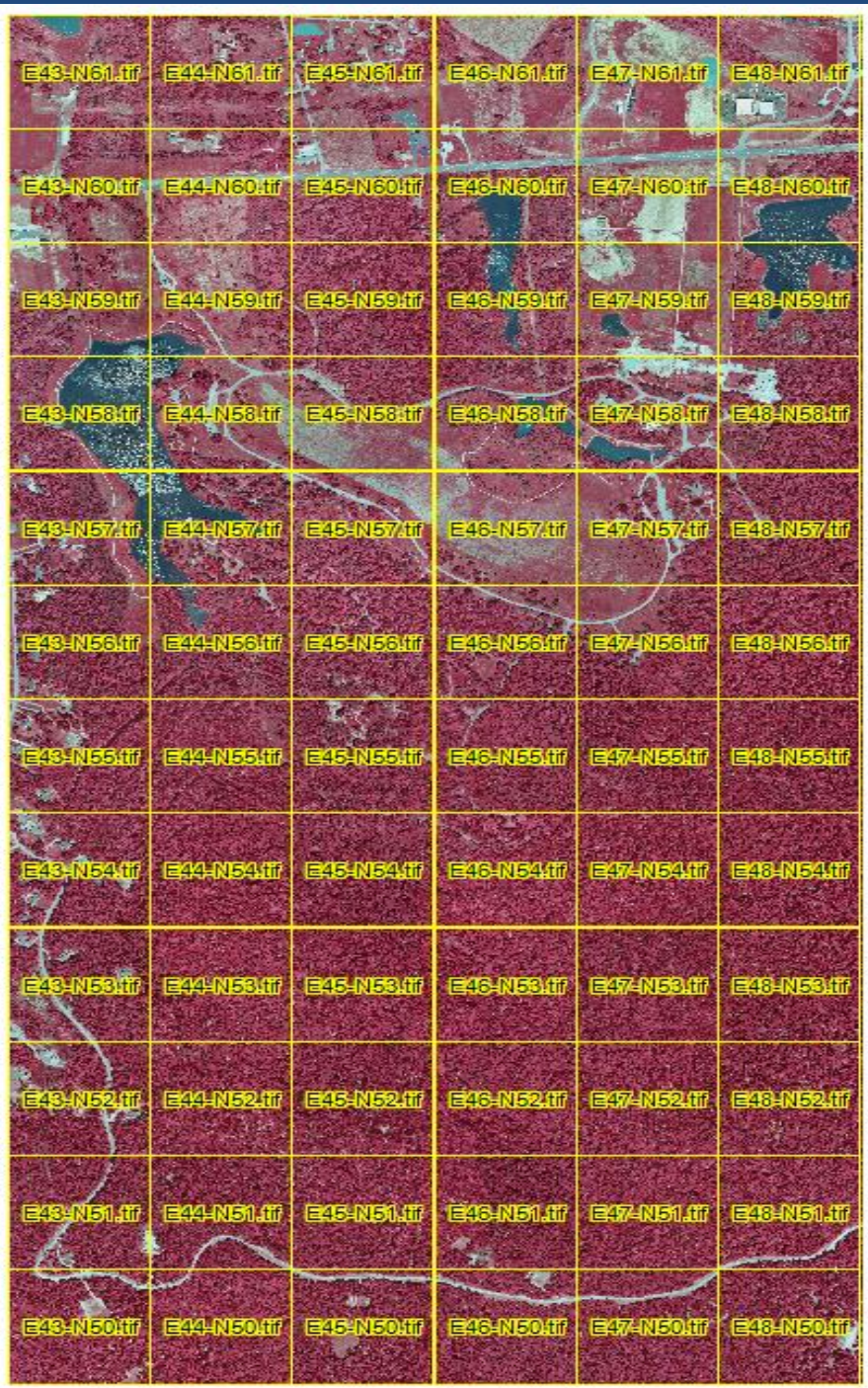
# AERIAL TARGETS & RESOLUTION ISSUES



AERIAL TARGETS VISIBLE IN COLOR AND CIR IMAGERIES



# DATA PROCESSING & GENERATION



**4 Lines 101 Exposures 1.97 " GSD**  
**72 Tiles of Color and CIR Orthophotos**  
**5-cm Resolution**  
**LiDAR Data 1-m Resolution**  
**9-Photo Control Points Used for AT**



# ACCURACY STANDARDS



Static OPUS HARN Point Precision	1- cm
Photo Control Points (Rapid Static)	3-cm
<b><u>5-cm Resolution Ortho Imagery Accuracy Estimate</u></b>	
a priori RMS	~ 15-cm
a posteriori RMSE	12.14-cm
<b><u>LiDAR Topographic Data Accuracy Estimate</u></b>	
a priori RMSE	Unknown
a posteriori RMSE	15-cm

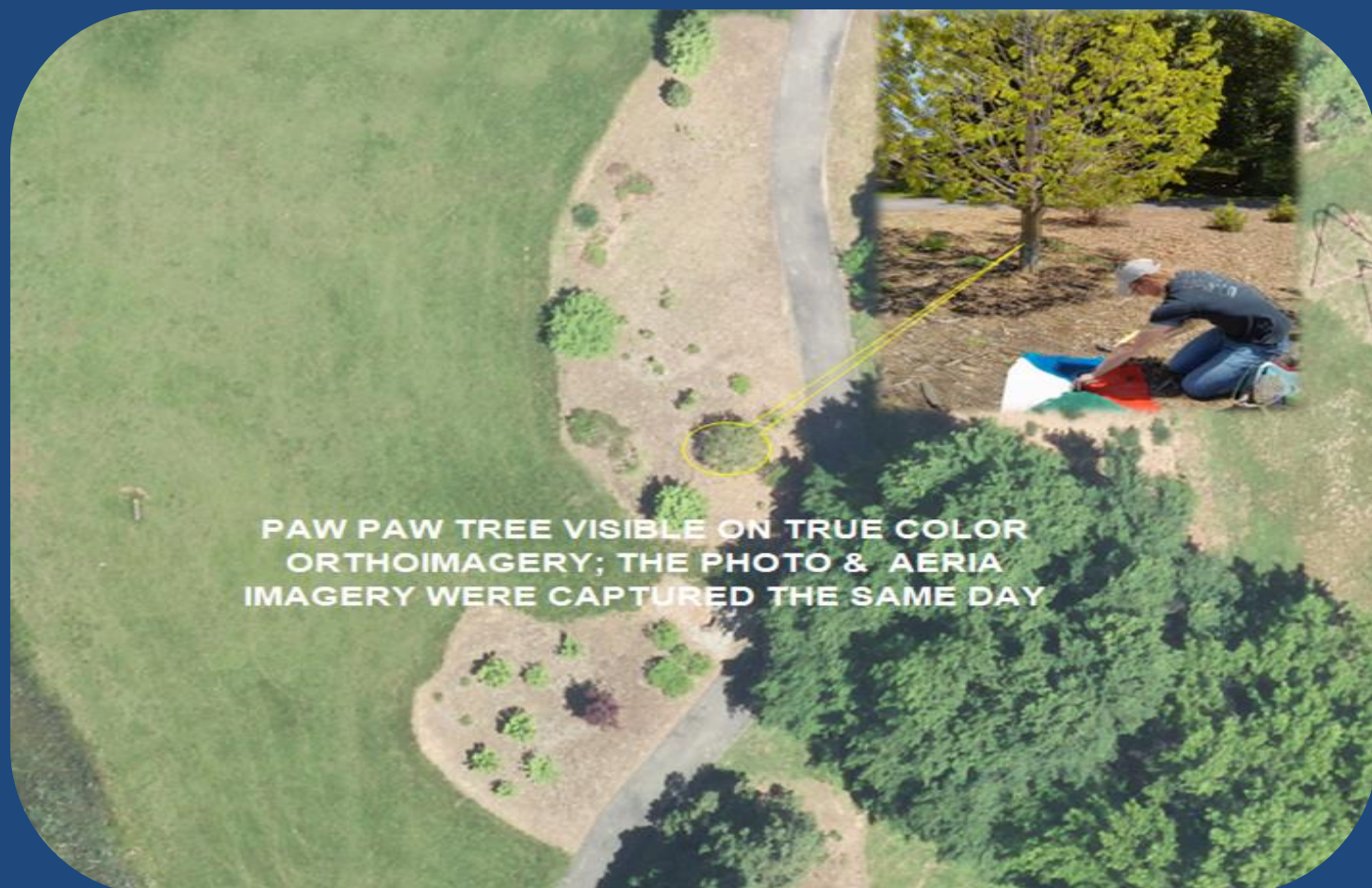


# PAWPAW TREES IN KENTUCKY





# PAWPAW TREES IN BERNHEIM KENTUCKY





# PAWPAW TREES AT BERNHEIM, KENTUCKY CONT'D..



PAWPAW TREES ARE FOUND ALONG CREEK AREAS SUCH AS THE HIGHLIGHTED AREA ABOVE IN THE GUERRILLA CREEK WATERSHED



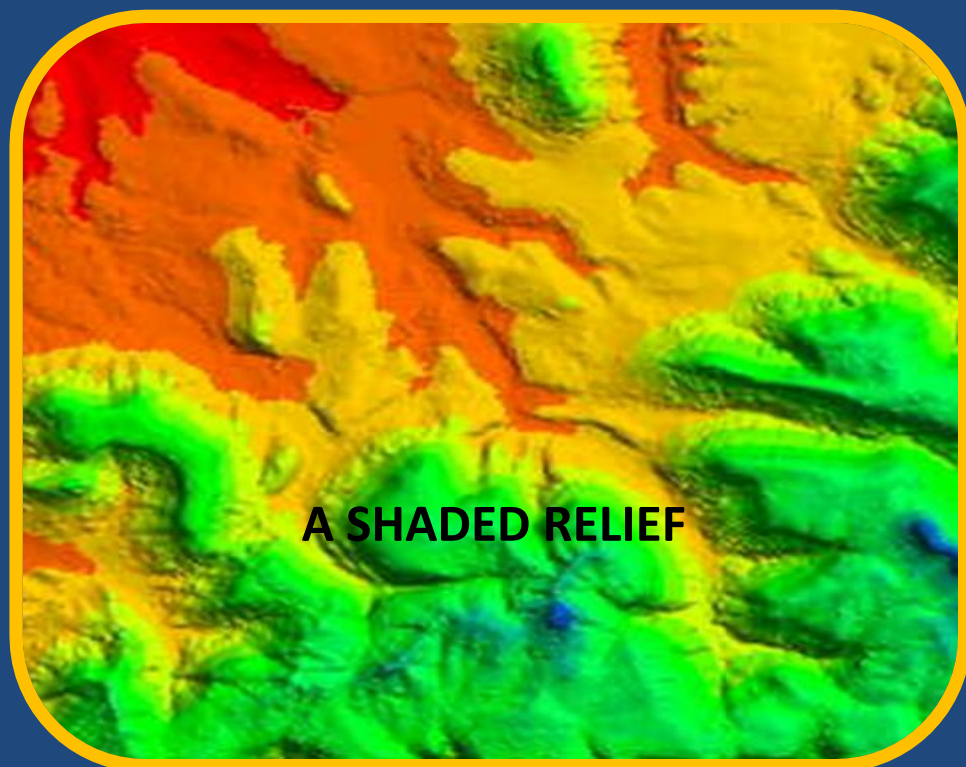
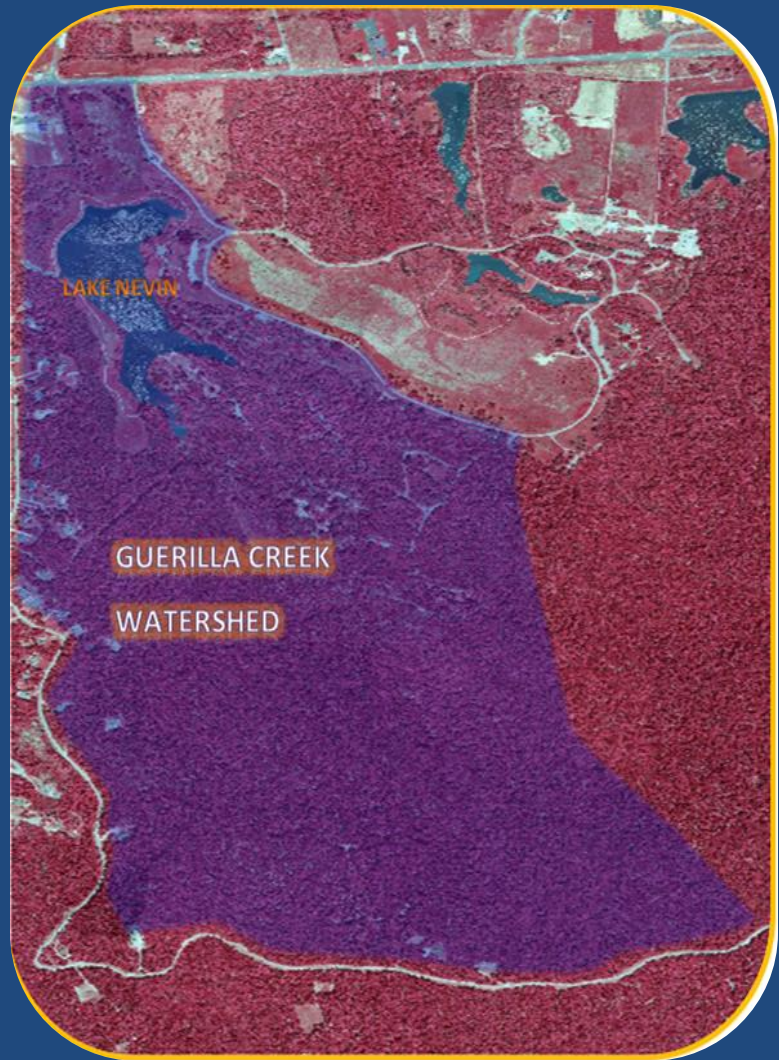
# PAWPAW TREES AT BERNHEIM, KENTUCKY CONT'D..



GROWN ALONG CREEKS AS UNDERSTOREY TREES  
(PICTURE JULY 2014)

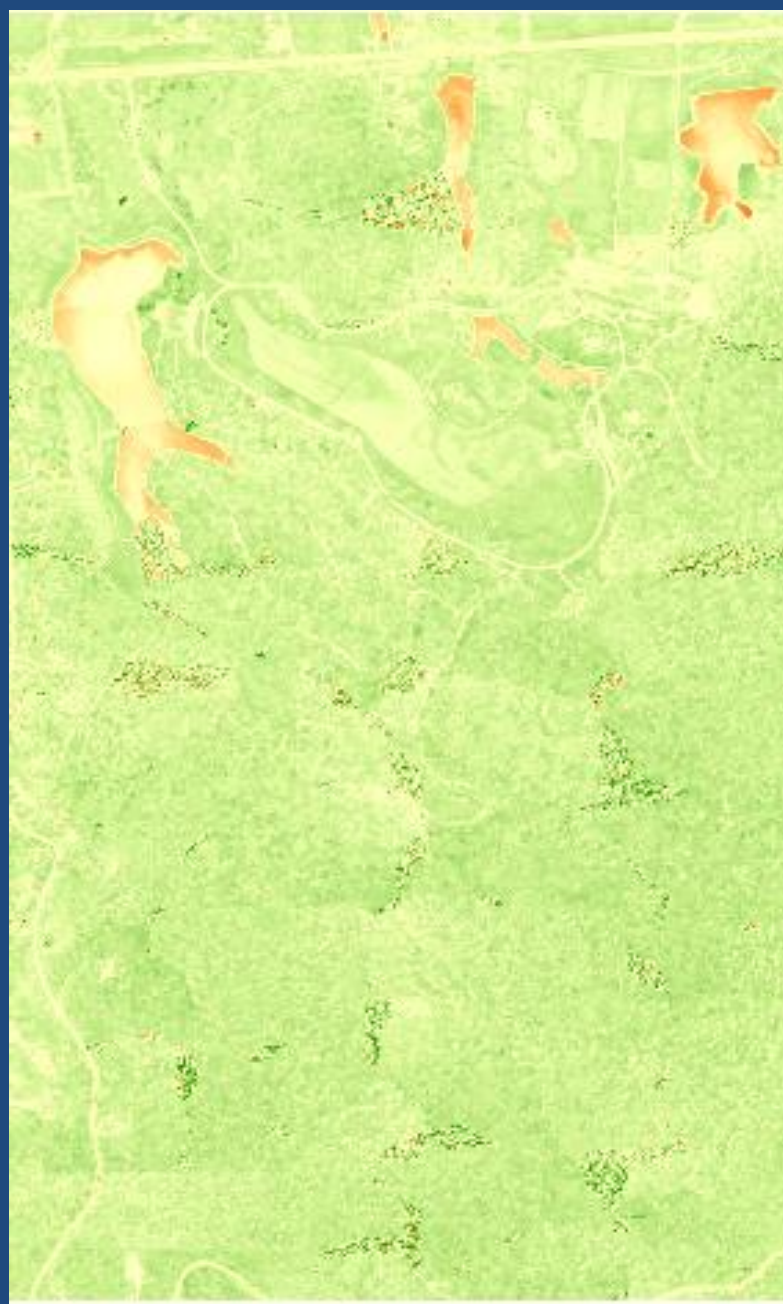


# GUERILLA CREEK WATERSHED ELEVATION DATA

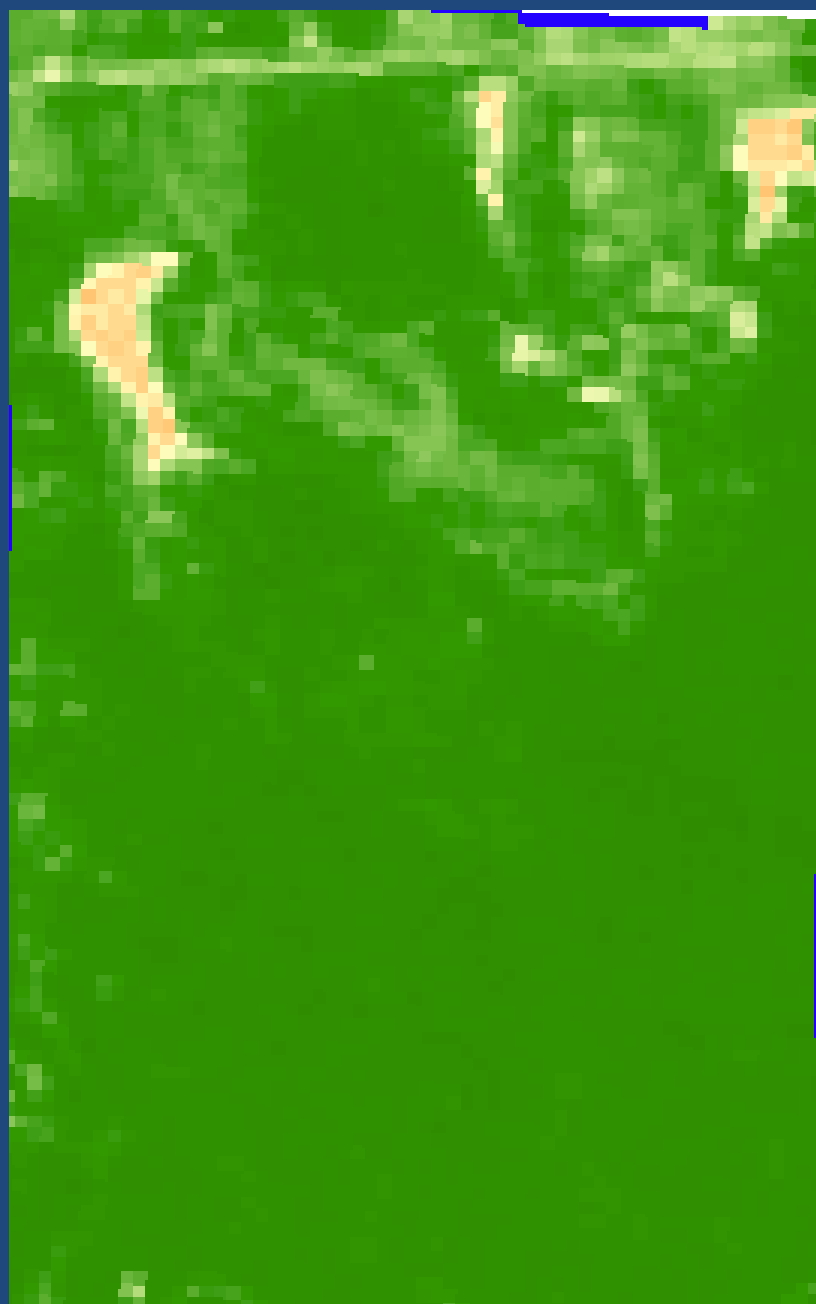




# GUERILLA CREEK WATERSHED NDVI DATA



NDVI from 5-cm Ortho Mosaic



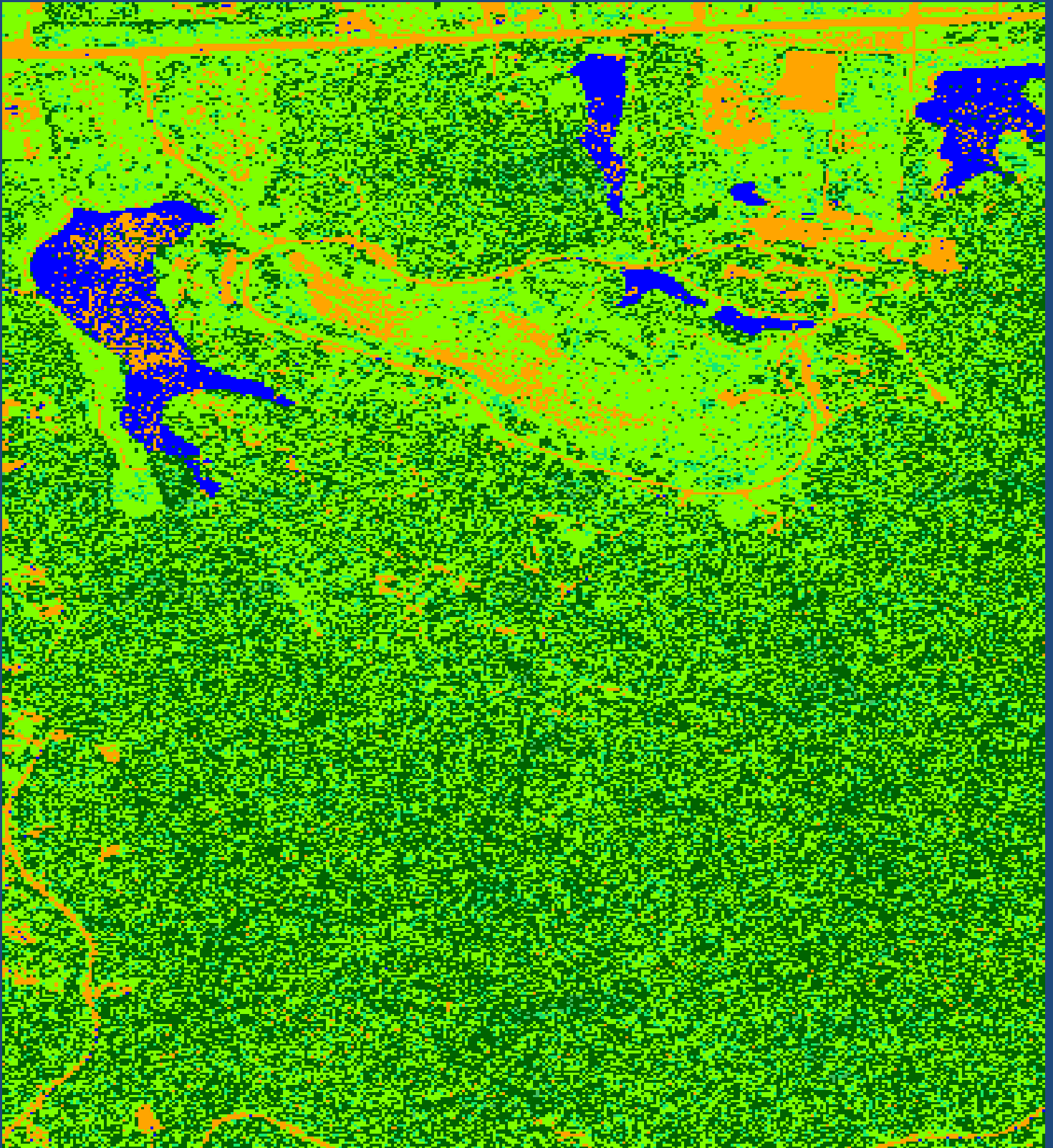
NDVI from 15-m LANDSAT ETM

NORMALIZED DIFFERENCE VEGETATION INDEX (NDVI) assists in checking the density of vegetation for any area of interest.

$$\text{NDVI} = (\text{NIR} - \text{VISIBLE RED}) / (\text{NIR} + \text{VISIBLE RED})$$



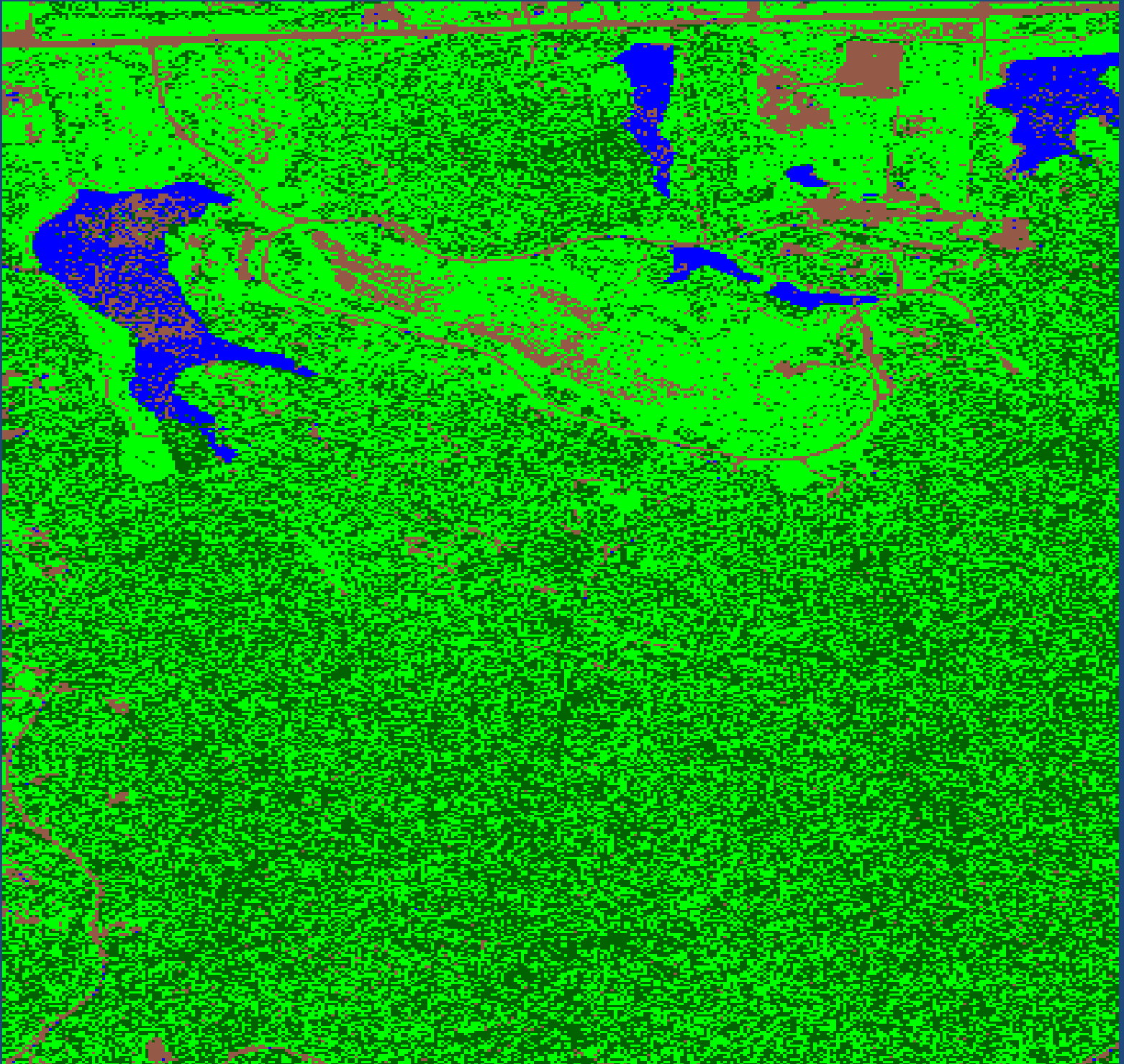
# GUERILLA CREEK STUDY AREA IMAGE CLASSIFICATION



UNSUPERVISED CLASSIFICATION WITH 60 CLASSES



# GUERILLA CREEK STUDY AREA IMAGE CLASSIFICATION CONT'D.



RECODED 4 CLASSES FROM THE 60 CLASSES:

1. Impervious
2. Trees
3. Grass
4. Water



# GUERILLA CREEK STUDY AREA IMAGE CLASSIFICATION CONT'D.



**Zoomed in Image**

Recoded 4 Classes From The 60 Classes:

1. Impervious Surface
2. Trees
3. Grass
4. Water



# PROBLEMS

**Both supervised and unsupervised classifications could not trace the pawpaw trees.**

**Despite the high resolution of the ortho imagery used , the classification techniques could not create a separate class of pawpaw.**

**The Near IR is not good enough to separate spectral signature of pawpaw with other vegetation.**

**Majority of pawpaw trees in the study area are located under story or under the canopy of taller trees.**



# NEXT STEPS

## PERFORM THE FOLLOWING TO OVERCOME THE PROBLEMS:

FLY THE STUDY AREA WITH HYPERSPECTRAL SENSOR

PERFORM A GROUND X-SECTION & L-SECTION SURVEYS ALONG THE GUERILLA CREEK (TERRESTRIAL LiDAR ALONG WITH TERRESTRIAL IMAGERIES OF PAWPAW PATCHES)

CAPTURE HIGH INTENSITY AIRBORNE LiDAR DATA & AIRBORNE IMAGERY

INTEGRATE AIRBORNE LiDAR INTENSITY, FIRST RETURN, LAST RETURN, INTERMEDIATE RETURN, AND TERRESTRIAL IMAGERIES TO CAPTURE SPECTRAL SIGNATURES FROM THE UNDERSTOREY PAWPAW TREES

COLLECT DIGITAL SPECTRAL SIGNATURES OF VARIETIES OF PAWPAW TREES AVAILABLE AT THE STUDY SITE

PERFORM CLASSIFICATION BUNDLING THE IMAGERIES FROM VARIOUS SENSORS

USE THE GROUND COLLECTED DATA FOR GROUND TRUTHING

UTILIZE THE SPECTRAL SIGNATURES OF THE VARIOUS PLANT SPECIES TO PERFORM A SUPERVISED CLASSIFICATION



# CONCLUSIONS

THE CURRENT ONGOING STUDY GUIDES TOWARDS **THE NEXT STEPS** TO OVERCOME THE PROBLEMS.

THE DATA SO COLLECTED WILL BE USEFUL FOR OTHER APPLICATIONS SUCH AS IMPERVIOUS SURFACE MAPPING, ENGINEERING MAPPING, LAND USE/COVER MAPPING, SOIL MAPPING, AND WATERSHED STUDIES.



# ACKNOWLEDGEMENTS

THE RESEARCH TEAM ACKNOWLEDGES THE KENTUCKY STATE UNIVERSITY FOR PROVIDING PARTIAL RESEARCH FUNDING AND BERNHEIM ARBORETUM AND RESEARCH FOREST FOR THE LOGISTICS PROVIDED DURING THE FIELD WORK OF THIS RESEARCH.

**The presentation team would like to thank the Organizer  
of the JACIE 'S Workshop at the ASPRS National  
Convention 2015.**

**THANK YOU FOR YOUR ATTENTIONS &  
PARTICIPATIONS!**